Motion control systems for high-speed vessels

D.A.Skorokhodov

282 p. Saint-Petersburg, CSRI "Elektropribor", 2000 ISBN 5-900780-29-5

The book considers peculiarities of motion control systems (MCS) operation and special features of high-speed vessels (air-cushion ships, hydrofoils, winged surface effect vehicles) dynamics, based on the results of full-scale trials of high-speed vessels and self-propelled models and mathematical simulation.

The studies on optimizing energy characteristics of MCS executive hydroelectric drives are presented. The substantiation is given for the model of optimization of energy characteristics of MCS executive hydroelectric drives for different types of high-speed vessels.

The results of advanced investigations on the development of control algorithms are given along with the results of MCS full-scale trials. Also presented is the method for correcting MCS algorithmic structures by the results of full-scale trials of vessels or their self-propelled models. This method allows for deriving new results in some algorithmic structures.

The possibility is shown for conformance of the extent of functional and elemental failures of MCS equipment and for finding of optimum, depending on high-speed vessel operation purposes.

Presented is the model of synthesizing MCS for high-speed vessels at early stages of designing.

The possibility of using a failure-free control performance criterion for multicriteria estimation of MCS efficiency is determined.

The method of estimation of level, scope and extent of high-speed vessel motion control automation is considered in the book, and the method of personnel habitability evaluation is also discussed.

The book is intended for technical and engineering employees and researchers dealing with ship motion control problems, as well as for teachers, post-graduates and senior students who specialize in this field.

CONTENTS

3

42

52

-

Introduction Chapter 1. Features of dynamics for the ships with dynamic support $\frac{1}{7}$ principles, their hardware and control systems 1.1. Air-cushion ship 1.2. Hydrofoil ship 1.3. Modes of use for DSP ships and for motion control systems operation Chapter 2. Efficiency improvement for control of the ships with dynamic 71

support principles

2.1. Efficiency improvement for DSP ships use

2.2. Improvement of DSP ships navigation safety	88
2.3. Operational availability of motion control systems	89
2.4. Efficiency of motion hardware use	90
2.5. Decrease of amount of work to be done by personnel on motion control and cost cutting	98
2.6. Structurization of forms and ways of DSP ships motion control	100
2.7. Choice of performance criterion for the DSP ships motion control system	107
2.8. Synthesis model for motion control systems	110
Chapter 3. Construction principles of motion control systems for the ships	126
with dynamic support principles in emergency	120
3.1. Air-cushion ship.	128
3.2. Hydrofoil ship	140
3.3. Ekranoplane craft	160
Chapter 4. Principles of functional-and-reliable and algorithmic	167
construction of motion control systems	_0/
4.1. Concept of functional-and-reliable construction for motion control systems	-
4.2. Algorithmic structure analysis for motion control systems	192
4.3. Vertical g-load sensors positioning at hydrofoil ships	209
Chapter 5. Synthesis of optimal power systems of motion control	213
5.1. Power channel insulation principle	-
5.2. Optimality criterion for power characteristics of automatic control system	217
5.3. Mathematical model of statistic wind-and-wave perturbations	223
5.4. Definition procedures for executive organ characteristics	228
5.5. Calculation of load moments on executive organs of ACS, HS, and EC control	233
5.6. Choice of power characteristics for ACS, HS, and EC automatic control systems	241
Conclusions	270
References	