**"Gyroscopy and Navigation" 2008**

**List of the materials published in the journal in 2008**

|  |  |  |
| --- | --- | --- |
|  |       | **№     page** |

|  |  |  |
| --- | --- | --- |
| **Bagaeva S.V., Belyaeva T.A., Belyaev Ya.V., Nekrasov Ya.A** | Cancellation of quadrature error in RR-type micromechanical gyroscope with the use of electrodes located above tooth area | **1       182** |

|  |  |  |
| --- | --- | --- |
| **Bakhonin K.A., Dzhandzhgava G.I., Trebukhov A.V., Vinogradov G.M.** | Hemispherical resonance gyro-based strapdown inertial navigation system | **1       22** |

|  |  |  |
| --- | --- | --- |
| **Barulina M.A., Dzhashitov V.E., Kalinin M.A., Pankratov V.M., Papko A.A.** | Mathematical model of micromechanical accelerometer with consideration for temperature effects, thermoelastic deflected mode and dynamic effects | **1       55** |

|  |  |  |
| --- | --- | --- |
| **Binder Ya. I.** | Compensation of gimballess gyroscopic inclinometer disturbances under continuous survey of small diameter holes | **2       62** |

|  |  |  |
| --- | --- | --- |
| **Blazhnov B.A., Emelyantsev G.I., Nesenyuk L.P., Stepanov A.P.** | Calibration of a gimballess inertial unit on fiber-optic or micromechanical gyros, comprised in an integrated system, during the spacecraft orbital flight | **2       39** |

|  |  |  |
| --- | --- | --- |
| **Boedecker Gerd** | Precision aircraft attitude determination with multi-antennae GPS receivers | **4       21** |

|  |  |  |
| --- | --- | --- |
| **Bolotin Yu.V., Golikov V.P., Larionov S.V., Trebukhov A.V.** | Calibration algorithms for a gimbal inertial navigation system | **3       13** |

|  |  |  |
| --- | --- | --- |
| **Buravlev A.S., Fedorov V.A., Korkishko Yu.N., Kostritskii S.M., Lisin L.G., Marchuk V.G., Morev I.V., Nesenyuk L.P., Paderin E.M., Ponomarev V.G., Prilutskii V.E.** | Navigation-grade interferometric fiber optical gyroscope | **1       171** |

|  |  |  |
| --- | --- | --- |
| **Emelyantsev G.I., Landau B.E., Levin S.L., Romanenko S.G.** | On refining the drift model of electrostatic gyros of the gimballess inertial attitude control system and their calibration procedure on a test bench and under orbiting space vehicle conditions | **1       43** |

|  |  |  |
| --- | --- | --- |
| **Graovac S., Stancic R.** | Integration of a low-accuracy strapdown inertial navigation system and GPS, the concept and results | **2       16** |

|  |  |  |
| --- | --- | --- |
| **Gutner I.Ye., Zhuravlev L.D., Zvorykin Ye.N., Molochnikov A.A., Orlov M.V.** | Calculation of the current glide slope angle for the aircraft landing on the aircraft-carrier deck | **4       40** |

|  |  |  |
| --- | --- | --- |
| **Hughes D., Legare D., Nikulin V., Skormin V., Sofka J.** | Demonstration of optical connectivity between two mobile platforms | **2       28** |

|  |  |  |
| --- | --- | --- |
| **Jaffe Randall, Qi Honghui, Rios Jose Antonio** | Test Results and Description of the MMQ-GTM, MEMS INS-GPS | **2       3** |

|  |  |  |
| --- | --- | --- |
| **Kulakova V.I., Nebylov A.V., Stepanov O.A** | H2/H∞ approach applied to aviation gravimetry problem | **2       53** |

|  |  |  |
| --- | --- | --- |
| **Maximov M.G., Shevchenko A.N.** | Computerized test bench for adjustment and testing of embedded electrostatic gyro thermostabilization system | **2       72** |

|  |  |  |
| --- | --- | --- |
| **Mikhailov N.V., Mikhailov V.F.** | An ambiguity resolution method for the GPS phase measurements at the spaceship relative navigation | **4       9** |

|  |  |  |
| --- | --- | --- |
| **Mikhailov N.V., Mikhailov V.F., Vasilev M.V.** | Autonomous navigation of space vehicles using GPS | **1       3** |

|  |  |  |
| --- | --- | --- |
| **Naumov Yu.E., Odintsov A.A., Vasilyeva V.B.,** | On one autonomous damping circuit for inertial navigation systems | **1       33** |

|  |  |  |
| --- | --- | --- |
| **Pelevin A.Ye.** | Parameter identification for a model of marine vehicle at the active control periodic motion | **4       29** |

|  |  |  |
| --- | --- | --- |
| **Peshekhonov V.G., Nesenyuk L.P., Gryazin D.G., Nekrasov Ya.A., Yevstifeyev M.I., Blazhnov B.A., Aksenenko V.D.** | Inertial units on micromechanical sensors. Development and tests results | **3       3** |

|  |  |  |
| --- | --- | --- |
| **Popova I.V., Lestev A.M., Semenov A.A., Ivanov V.A., Rakityansky O.I., Burtsev V.A.** | Encapsulated micromechanical gyros and accelerometers for digital navigation and control systems | **3       27** |

|  |  |  |
| --- | --- | --- |
| **Shalimov L.N., Deryugin S.F., Belsky L.N.** | Academician N.A. Semikhatov and his role in designing rocket and space technology and in developing applied science. To the 90th birth anniversary (1918 - 2002) | **4       116** |

|  |  |  |
| --- | --- | --- |
| **Taranovsky D.O.** | Bench calibration of pendulous floated accelerometers of a shipborne inertial navigation system | **4       56** |

|  |  |  |
| --- | --- | --- |
| **Terentyev I.A.** | Functional diagnosis and testing of a gimbal inertial navigation system servosystem | **4       49** |

|  |  |  |
| --- | --- | --- |
| **Udovikov A.S.** | Investigation of the dimensional stability of high-accuracy spherical thin-walled beryllium rotors | **1       90** |

|  |  |  |
| --- | --- | --- |
| **Velikoseltsev A., Schreiber U., Kluegel T., Voigt S., Graham R.** | Sagnac interferometry for the determination of the Earth rotation in geodesy and seismology | **3       37** |

|  |  |  |
| --- | --- | --- |
| **Yakimovsky D.O.** | Increasing accuracy of motor-handwheel moment control | **3       46** |

**Brief notes**

|  |  |  |
| --- | --- | --- |
| **Bogdanov M.B., Prohortsov A.V., Saveliev V.V., Smirnov V.A., Chepurin A.A.** | Analysis of operating conditions and measurement channel errors influence on strapdown attitude orientation system accuracy | **3       53** |

|  |  |  |
| --- | --- | --- |
| **Buravlev A.S., Egorov D.A., Lisin L.G.** | Fiber optical gyroscopes under magnetostatic field conditions | **3       59** |

|  |  |  |
| --- | --- | --- |
| **Vasyukov S.A.** | On the rotor charge influence on stability of rotary centering in a cylinder electrostatic suspension | **3       64** |

|  |  |
| --- | --- |
| **Abstracts** of papers by the participants in the youth section of the 14th Saint Petersburg International Conference on Integrated Navigation Systems | **1       95** |

**Jubilee 10th Conference of Young Scientists
"Navigation and Motion Control"**

|  |  |
| --- | --- |
| Abstracts of the papers | **2       78** |

**Materials of the 15th Saint Petersburg International Conference
on Integrated Navigation Systems**

|  |  |
| --- | --- |
| Abstracts of the papers | **3       71** |

|  |  |
| --- | --- |
| Professor H. Sorg's speech at the Conference closing ceremony | **3       98** |

|  |  |
| --- | --- |
| 2nd Russian Multiconference on Control Problems (2RMCCP-2008) | **4       66** |

**26th Conference in memory of N.N.Ostryakov**

|  |  |
| --- | --- |
| *Abstracts of the papers* | **4       67** |

**International Public Association
The Academy of Navigation and Motion Control
O f f i c i a l     i n f o r m a t i o n**

|  |  |
| --- | --- |
| High technologies form strong Russia's future (on scientific and practical conference of senior pupils) | **2       113** |

|  |  |  |
| --- | --- | --- |
| **Lynch D.** | Northrop Grumman's view on development of the navigation technologies | **3       102** |

|  |  |
| --- | --- |
| The 25th General Meeting of the Academy of Navigation and Motion Control | **3       99** |

|  |  |
| --- | --- |
| The 26th General Meeting of the Academy of Navigation and Motion Control | **4       113** |

|  |  |
| --- | --- |
| The visiting session of the Academy Presidium at the town of Serpukhov, Moscow region | **2       111** |

|  |  |  |
| --- | --- | --- |
| **Veremey E.I.** | Conference on the MATLAB package application to research and education | **1       103** |

**History pages**

|  |  |  |
| --- | --- | --- |
| **Sorg Helmut W., Wagner Jorg** | The machine of Bohnenberger | **1       107** |

**New books**

|  |  |
| --- | --- |
| About monograph "Precision controllable test benches for dynamic tests of gyroscopic devices" | **3       107** |

|  |  |
| --- | --- |
| About D.M. Kalihman's book "Precision controllable test benches for dynamic tests of gyroscopic devices" | **4       119** |

**Information**

|  |  |
| --- | --- |
| About book "Precision gas-lubricated bearings" by Boldyrev Yu.Ya., Filippov A.Yu., Grigoriev B.S., Luchin G.A., Panich T.V., Sipenkov I.E., , Zablotsky N.D. *(feedback from readers)* | **1       115** |

|  |  |
| --- | --- |
| Centrifuges as the main means for setting a constant linear acceleration in the range above 1 g | **4       125** |

|  |  |
| --- | --- |
| Russian and international conferences, symposia and exhibitions | **1       116** |

|  |  |
| --- | --- |
| Russian and international conferences, symposia and exhibitions | **2       119** |

|  |  |
| --- | --- |
| Russian and international conferences, symposia and exhibitions | **3       115** |

|  |  |
| --- | --- |
| Russian and international conferences, symposia and exhibitions | **4       121** |

|  |  |  |
| --- | --- | --- |
| **Stepanov O.A.** | 17th IFAC World Congress. Seoul-2008 | **3       109** |

|  |  |  |
| --- | --- | --- |
| **Stepanov O.A.** | International satellite navigation forum 2008 | **2       115** |