INTERNATIONAL WORKSHOP NAVIGATION & MOTION CONTROL 26-30 September 2016, Russia

International Workshop on Navigation and Motion Control

September 26 – 30, 2016 PROGRAM



КАФЕДРА ИНФОРМАЦИОННО-НАВИГАЦИОННЫХ СИСТЕМ





INTERNATIONAL WORKSHOP NMC 2016 NAVIGATION & MOTION CONTROL 26-30 September 2016, Russia



CO-SPONSORED BY:

State Research Center of the RF Concern CSRI Elektropribor, JSC **Russian Foundation for Basic Research** International Public Association - Academy of Navigation and Motion Control St. Petersburg Group of the Russian National Committee on Automatic Control St. Petersburg Electrotechnical University "LETI"



INTERNATIONAL WORKSHOP NMC 20016 NAVIGATION & MOTION CONTROL 26-30 September 2016, Russia

September 26 (Monday)

8.30
9.00
13.00
14.00 - 15.00
15.00 - 15.10

15.10	-	16.00
16.00	-	16.50
16.50	-	17.00
17.00	-	17.50

18.00 - 19.00

September 27 (Tuesday)

09.00 -	10.00
10.00 -	10.45

10.45 - 11.30

11.30 - 11.45 11.45 - 12.10

12.10 - 12.35

Lunch

B.S. Rivkin (Concern CSRI Elektropribor, JSC, Russia) GNSS. Systems and technologies

R. Piche (Tampere University of Technology, Finland) Indoor positioning particle filter

Break

Dinner

V.G. Peshekhonov (Concern CSRI Elektropribor, JSC, Russia) Prospects of gyro technologies

Breakfast Session 2. Chair A.V. Motorin (Concern CSRI Elektropribor, JSC; ITMO University, Russia) S.G. Revnivykh (Reshetnev Information Satellite Systems Corporation, JSC, Russia) State and development of GLONASS as a part of the world GNSS

G.F. Trommer (KIT University, Germany; ITMO University, Russia) Image based navigation using landmarks

Break G.F. Trommer (KIT University, Germany; ITMO University, Russia), N. Kronenwett (KIT University, Germany) Motion monitoring based on a finite state machine for precise indoor localization

M. Mansour (ITMO University, Russia) Nonlinear filtering methods for indoor navigation

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Meeting at 9a, Bolshaya Posadskaya St., Concern CSRI Elektropribor, JSC Bus departure

Arrival at the destination

Welcome and introduction. O.A. Stepanov (Concern CSRI Elektropribor, JSC; ITMO University, Russia)

Session 1. Chair Yu.A. Litvinenko (Concern CSRI Elektropribor, JSC; ITMO University, Russia)

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September 27 (Tuesday)	
12.35 - 13.00	O.V. Zaitsev (ITMO University; CSRI Elektropribor, GNSS data processing under uncertainty of their
13.00 - 14.30	Lunch
	Session 3. Chair A.S. Nosov (Concern CSRI Elek ITMO University, Russia)
14.30 - 15.15	R. Piche (Tampere University of technology, Finla Off-line estimation of state space model parameter
15.15 - 15.40	G. Scholz, S. Prophet, M. Popp (KIT University, C. G.F. Trommer (KIT University, Germany; ITMO Un Guiding quadrotors through unknown environme
15.40 - 16.05	T. Wald, G. Scholz (KIT University, Germany), G.F. Trommer (KIT University, Germany; ITMO Un Automatized hybrid control optimization of a non
16.05 - 16.30	G.F. Trommer (KIT University, Germany; ITMO Un J. Atman (KIT University, Germany) Motion navigation aiding by a hybrid laser-camer aerial vehicles
16.30 - 16.55	Lyan Cin (ITMO University, Russia), Yu.A. Litvinenko (Concern CSRI Elektropribor, JS Complementary filter for estimation of inertial de
16.55 - 17.10	Break
17.10 - 18.20	N.T. Zhigunova (Concern CSRI Elektropribor, JSC Writing scientific papers in English: Grammar and
18.20 - 19.20	Dinner
September 28 (Wednesday)	
09.00 - 10.00	Breakfast
	Session 3. Chair G.Scholz (KIT University, Germ
10.00 - 10.20	V.V. Bogomolov (ITMO University, Russia) Approximate expressions for accuracy of a strap

in autonomous mode

Russia) models

ktropribor, JSC;

and) ters Germany), niversity, Russia) ent using potential fields

niversity, Russia) -linear MAV niversity, Russia),

ra motion estimator for micro

SC; ITMO University, Russia) evice errors

C, Russia) nd vocabulary

nany)

odown inertial navigation system

INTERNATIONAL WORKSHOP NMC 20016 NAVIGATION & MOTION CONTROL 26-30 September 2016, Russia

September 28 (Wednesday)

10.20 - 10	0.40
10.40 - 11	.00
11.00 - 11	.20
11.20 - 11	.40
11.40 - 11	1.55
11.55 – 12	2.10
12.10 - 12	2.25
12.25 - 12	2.40
12.40 - 14	4.10
14.10 - 15	5.00
15.00 - 1	5.50
15.50 - 10	5.00
16.00 - 10	5.25
16.25 - 10	5.50

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N.J. Mrisho (Saint Petersburg Electrotechnical University "LETI", Russia) Searching for a suitable frequency estimation technique in estimating the Earth rotation rate with the large ring laser (G-ring laser) data

B. Baruti (Saint Petersburg Electrotechnical University "LETI", Russia) Solar balloon based satellite navigation system

uncertainty

Break

I.Yu. Merkulova, M. Mansour (ITMO University, Russia) About the practical training at Tampere University of technology (Finland)

G. Scholz (KIT University, Germany) On the 2016 DGON Inertial Sensors and Systems (ISS) Symposium Gyro Technology

A.A. Anikina (Concern CSRI Elektropribor, JSC, Russia), **O.V. Zaitsev** (ITMO University; CSRI Elektropribor, Russia) On the 25th International Scientific and Technical Conference Current Technologies in the Problems of Control, Automation and Data Processing

E.O. Kishko (Concern CSRI Elektropribor, JSC, Russia) Workshop on Navigation and Motion Control

Lunch

S.A. Kolyubin, A.A. Bobtsov (ITMO University, Russia) Control in cyber physical systems. Myths and legends or subjective opinion of speakers

I.B. Furtat (Institute of Problems of Mechanical Engineering Russian Academy of Sciences (IPME RAS); ITMO University, Russia) Control of multi-agent systems and its application for control of multi-machine power systems

Break

S.A. Zagrebin (Concern CSRI Elektropribor, JSC; ITMO University, Russia) Simulation of towed antenna dynamics

A.S. Voronov (Concern CSRI Elektropribor, JSC; ITMO University, Russia) Increasing the strength of deep sea ships' electromagnetic logs

E.V. Lukoyanov (ITMO University, Russia)

Using fuzzy interacting observers for fault diagnosis in systems with parameter

Session 4. Chair V.V. Tsodokova (Concern CSRI Elektropribor, JSC, Russia)

Session 5. Chair D.P. Eliseev (Concern CSRI Elektropribor, JSC, Russia)

INTERNATIONAL WORKSHOP NMC 20016 NAVIGATION & MOTION CONTROL 26-30 September 2016, Russia

September 28 (Wednesday)

16.50 - 17.15 17.15 - 17.40 17.40 - 18.30 18.30 - 19.30 September 29 (Thursday) 09.00 - 10.0010.00 - 16.0016.00 - 17.0020.00 September 30 (Friday) 09.00 - 10.00 10.00 - 10.4510.45 - 11.10 11.10 - 11.35 11.35 - 12.00 12.00 - 13.00 13.00 - 14.00 14.00 - 14.20 16.00

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A. Ndayishimiye (Saint Petersburg Electrotechnical University "LETI", Russia) Gyrocompass with auto-compensated instrumental errors N.K. Kulachenkov (Concern CSRI Elektropribor, JSC, Russia) Nuclear magnetic resonance gyroscope. A brief review Discussion of the papers submitted for publication in the Proceedings of the Conference of Young Scientists Navigation and Motioncontrol Dinner

Breakfast Cultural and Entertainment program Lunch Banquet

Breakfast

Session 6. Chair Ya.V. Belyaev (Concern CSRI Elektropribor, JSC, Russia) M.M. Pilipko (Peter the Great St. Petersburg Polytechnic University, Russia) Design of sigma-delta analog-to-digital converter

D.V. Kostygov (Concern CSRI Elektropribor, JSC, Russia) Digital design flow for MEMS accelerometer

Yu.A. Andryakov (Concern CSRI Elektropribor, JSC, Russia) Design and optimization of MMA front-end

A.A. Anikina (Concern CSRI Elektropribor, JSC, Russia) Limitations of CMOS technology in switched-capacitors DAC design

Discussion of the papers submitted for publication in the Proceedings of the Conference of Young Scientists Navigation and Motioncontrol

Lunch

Closing Ceremony **O.A. Stepanov** (Concern CSRI Elektropribor, JSC; ITMO University, Russia) Departure to Saint-Petersburg





WORKSHOP WORKING GROUP IN CSRI ELEKTROPRIBOR **CONTACT INFORMATION:**

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Workshop Manager - Ekaterina Kishko



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INTERNATIONAL LABORATORY «INTEGRATED NAVIGATION AND ATTITUDE REFERENCE SYSTEMS»

International Laboratory «Integrated navigation and attitude reference systems» was founded under the auspices of "Information and navigation system" Department with The State Research Center of the Russian Federation - Concern CSRI Elektropribor, JSC (http://www.elektropribor.spb.ru/). It is the leading research institute in Russia in the area of high-precision navigation, gyroscopy, gravimetry. The laboratory is engaged in research and development of integrated navigation and attitude reference systems for various types of vehicles.

RESEARCH AREAS:

CONTACTS:

- Improvement of methods for processing of redundant navigation information.
- Development of methods for designing small-sized inertial satellite integrated navigation and attitude reference systems for various types of vehicles and robotic devices.
- Development of methods for designing small-sized systems for individual navigation and guidance.
- Improvement of GNSS receivers.
- Development and design of inertial sensors for navigation systems using up-to-date computer technologies.

HEADS OF THE INTERNATIONAL LABORATORY:

Oleg Stepanov Professor, D.Sc. in Engineering (Russian Scientific Degree "Doctor of Technical Sciences") ITMO University

Gert Trommer Director, Professor, Ph.D Institute of Systems Optimization of Karlsruhe Institute of Technology, Germany



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